

(1/2)

Exam solution manual  
(12/01/15 SS4285)

Q1)  $G(s) = C(sI - A)^{-1}B + D = \begin{bmatrix} 1 & 0 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} s+1 & -1 \\ -3 & s+1 \end{bmatrix}^{-1} \begin{bmatrix} -1 & 1 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$

$G(s) = \frac{1}{s^2 + 2s - 2} \begin{bmatrix} -s-1 & s(s+3) \\ s-2 & 2 \end{bmatrix} \Rightarrow \det G(s) = \frac{-s-1}{s^2 + 2s - 2}$   
(1P)

$z = 1$ ;  $p_1 = 0.73$ ,  $p_2 = -2.73$   
not a minimum phase not stable  
(1P)

Q2) a)  $A = \begin{bmatrix} 0 & a_2 + k_1 a_3 \\ a_1 & k_1 a_4 \end{bmatrix}$ ;  $B = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$ ;  $C = [c \ 0]$ ;  $D = c$   
(1P)

b)  $\det(\lambda I - A) = \begin{vmatrix} \lambda & -1 - k_1 \\ -1 & \lambda - 2k_1 \end{vmatrix} = \lambda(\lambda - 2k_1) - (1 + k_1) =$

c)  $R_2 = [B \ AB] = \begin{bmatrix} b_1 & -2(1+k_1) \\ -2 & b_1 - 4k_1 \end{bmatrix}$   
 $\lambda^2 - 2k_1\lambda - (1+k_1) = s^2 + 2s + 0$   
 $k_1 = -1$  (1P)

$\det(R) = b_1^2 + 4b_1 = 0 \Rightarrow b_1 = 0$  or  $b_1 = -4$   
We lose contr. if  $b_1 = \begin{bmatrix} 0 \\ -4 \end{bmatrix}$   
 $R_2 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \Rightarrow$  rank deficiency  $\Rightarrow$  not observable  
Not a minimal order realization and independent of  $b_1$ ! (1P)

d)  $A = \begin{bmatrix} 0 & 0 \\ 1 & -2 \end{bmatrix}$ ;  $B = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$ ;  $C = [1 \ 0]$ ;  $D = 1$

$\text{eig}(A) \rightarrow \begin{bmatrix} -2 \\ 0 \end{bmatrix} \Rightarrow$  e.g.  $v_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ ;  $v_2 = \begin{bmatrix} 0.89 \\ 0.44 \end{bmatrix}$  eigenvectors are not unique  $\tilde{B}, \tilde{C}$

$T^{-1} = \begin{bmatrix} 0 & 0.89 \\ 1 & 0.44 \end{bmatrix}$  (1P)  $T = \frac{\text{adj}(T^{-1})}{\det(T^{-1})} = \begin{bmatrix} -0.5 & 1 \\ 1.18 & 0 \end{bmatrix}$  (1P)

$\tilde{A} = TAT^{-1} = \begin{bmatrix} -2 & 0 \\ 0 & 0 \end{bmatrix}$ ;  $\tilde{B} = TB = \begin{bmatrix} -2.5 \\ 1.18 \end{bmatrix}$ ;  $\tilde{C} = [0 \ 0.89]$ ;  $D = \tilde{D}$   
(1P)

e)  $y(t) = \tilde{C} e^{\tilde{A}t} x_0 = [0 \ 0.89] \begin{bmatrix} e^{-2t} & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \Rightarrow y(0) = y(0) = -0.89$  (1P)

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$$\bar{P} = \begin{bmatrix} p_1 & p_2 \\ p_2 & p_3 \end{bmatrix}$$

Q3)  $\bar{P} - A\bar{P}A^T - NUN^T + A\bar{P}C^T(W + C\bar{P}C^T)^{-1}C\bar{P}A^T = 0$

a) 
$$\begin{bmatrix} -2p_2 - p_3 - 1 + p_2(p_1 + p_2/p_1 + p_1 - B^{-1} + X) & \\ -p_3 + p_2^2/p_1 + p_2 + 1 & -1 + p_2^2/p_1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$\Rightarrow p_1 = p_2 = p_3 = 1 \quad \bar{P} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = \bar{P}^T \geq 0$

$\bar{L} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

b)  $A - \bar{L}C = \begin{bmatrix} -1 & 1 \\ -1 & 1 \end{bmatrix} \Rightarrow (\lambda I - A + \bar{L}C) \Rightarrow \lambda_1 = \lambda_2 = 0$

Q4)  $A=1; B=[1 \ 1]; Q_x=1; Q_u = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

discrete-time LQR; discrete-time CARE

$A^T P A - P - A^T P B (Q_u + B^T P B)^{-1} B^T P A + Q_x = 0$

$\Rightarrow P - P - P \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \left( \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \end{bmatrix} P \begin{bmatrix} 1 & 1 \end{bmatrix} \right)^{-1} \begin{bmatrix} 1 \\ 1 \end{bmatrix} P + 1 = 0$

a)  $2p^2 - 2p - 1 = 0 \quad p = 1.36 \quad K = (B^T P B + Q_u)^{-1} B^T P A = \begin{bmatrix} 0.36 \\ 0.36 \end{bmatrix}$

b)  $A - BK = 1 - 2 \cdot 0.36 = 0.28 \quad (1p)$

Q5)  $G_{yr} = \frac{G_n F}{1 + G_n C} = \frac{3}{(s+1)(s+2+3C)(s+3)}$

$y_{\infty} = \lim_{s \rightarrow 0} G_{yr} \cdot \frac{1}{s} = \frac{3}{2+9C} \Rightarrow C = \frac{1}{3} \quad (1p)$

$= G_n + \Delta a \Rightarrow \Delta a = \frac{1 - 3(s+3)(s+2)}{(s+1)(s+2)^2} \quad (1p)$

$= (1 + \Delta u) G_n \Rightarrow \Delta u = \frac{\Delta a}{G_n} = \frac{1 - 3(s+3)(s+2)}{3(s+3)(s+2)} \quad (1p)$

Q6)  $b = \sqrt{2}, b_1 = 0.5, p_2 = 0.5, a = -1.5$

$u = -5\sqrt{2}x = -Q_u^{-1} \cdot B^T \cdot \bar{P} x \Rightarrow \bar{P} = 5 \quad (1p)$

$\bar{P} = \bar{P}^T + 0 \quad \bar{P} = 2(b^2 - 1 \cdot b^2) = 0$

$q_x = ?$

$q_u = 1$

$\dots = 1 \quad (1p)$